



NIRB Uuktuttinga Ihivriuqhikhamut #125477

Testing an industrial vessel of opportunity model for ship-time access to survey Canadian Arctic gateway ecosystems using baited remote underwater video

Uuktuttinga Qanurittuq: New

Havaap Qanurittunia: Scientific Research

Uuktuttinga Ublua: 7/26/2019 1:38:50 PM

Period of operation: from 0001-01-01 to 0001-01-01

Piumayaat Angirutinga: from 0001-01-01 to 0001-01-01

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QANURITTUT

Tukihiannaqtunik havaariyauyumayumik uqauhiuyun

Qablunaatitut: This research project has been proposed by Dr. Jonathan A. D. Fisher, a Research Scientist within Memorial University of Newfoundland's Centre for Fisheries Ecosystems Research. Jonathan is based in St. John's, Newfoundland and Labrador. Jonathan focuses his research and student training on helping to understand changes in marine ecosystems of Canada's Arctic and sub-Arctic seas. There are two main goals of this research project. The first goal is to test whether baited remote underwater video lander (baited with squid to attract fish, sharks and invertebrates) can be deployed and left to record for up to 10 hours from the MSV Botnica icebreaker as it escorts large iron ore ships into and out of Eclipse Sound, Nunavut. The second goal is to work with other interested researchers to use the video data collected at the sea bottom to identify marine species and their habitats within what is expected to become the Tallurutiup Imanga/Lancaster Sound National Marine Conservation Area. This work involves putting one researcher and an underwater video camera system onto a ship for one month. No animals will be harmed in this project and no equipment will be left in Nunavut. The beauty and diversity of the deep sea in eastern Nunavut has largely been out of sight to scientists. That is partly because of the challenge and expense of collecting images from deep, cold habitats. However, my laboratory has demonstrated how useful baited remote underwater video can be to quantify local abundances of Greenland sharks and reveal benthic habitats, invertebrates and fishes in the eastern Canadian Arctic. This project grew from an offer from the marine transportation industry to develop a scientific sampling program that fits within the MSV Botnica as it fulfils its primary escort mission. This research model for Arctic ship time access has potential to grow in the coming years, yielding significant contributions from industry partners to science programs in areas where required icebreaker ship time is otherwise extremely expensive. Most importantly, this means this model of cooperation means that fewer icebreakers would be needed in Nunavut waters if science and transportation companies can work together. This project is requested to take place in the offshore waters of Eclipse Sound and Milne Inlet within the Qikiqtaaluk region of Nunavut. The closest community to the proposed project site is Pond Inlet, Nunavut. The project is proposed to take place during the most ice-free times of year, in the later summer and early fall (between late July and late October, as weather permits).

Uviititut: Ce projet de recherche a été proposé par Jonathan A. D. Fisher, chercheur scientifique au Centre de recherche sur les écosystèmes des pêches de l'Université Memorial de Terre-Neuve. Jonathan est basé à St. John's, à Terre-Neuve-et-Labrador. Jonathan concentre sa recherche et sa formation sur l'aide à la compréhension des changements dans les écosystèmes marins des mers arctiques et subarctiques du Canada. Ce projet de recherche a deux objectifs principaux. Le premier objectif est de vérifier si un atterrisseur vidéo sous-marin isolé appâté (avec un calmar pour attirer les poissons, les requins et les invertébrés) peut être déployé et enregistré pendant 10 heures au maximum depuis le brise-glace MSV Botnica lorsqu'il escorte de gros navires hors du détroit d'Eclipse, au Nunavut. Le second objectif est de travailler avec d'autres chercheurs intéressés pour utiliser les données vidéo recueillies au fond de la mer afin d'identifier les espèces marines et leurs habitats dans ce qui devrait devenir l'aire marine nationale de conservation de Tallurutiup Imanga / Lancaster Sound. Ce travail consiste à installer un chercheur et un système de caméra vidéo sous-marine sur un navire pendant un mois. Aucun animal ne sera blessé dans ce projet et aucun équipement ne sera laissé au Nunavut. La beauté et la diversité des eaux profondes de l'est du Nunavut ont été en grande partie perdues de vue pour les scientifiques. Cela est en partie dû au défi et aux dépenses liés à la collecte d'images provenant d'habitats profonds et froids. Cependant, mon laboratoire a démontré l'utilité d'une vidéo sous-marine éloignée avec appâts pour quantifier les abondances locales de requins du Groenland et révéler les habitats benthiques, les invertébrés et les poissons de l'est de l'Arctique canadien. Ce projet découle d'une offre de l'industrie du transport maritime d'élaborer un programme d'échantillonnage scientifique qui s'intègre au MSV Botnica dans la réalisation de sa mission principale d'escorte. Ce modèle de recherche sur l'accès à l'heure des navires arctiques pourrait se développer dans les années à venir, apportant une contribution importante des partenaires de l'industrie aux programmes scientifiques dans des domaines où la durée requise des navires brise-glace est extrêmement coûteuse. Cela signifie surtout que ce modèle de coopération signifie que moins de brise-glace seront nécessaires dans les eaux du Nunavut si les entreprises de la science et du transport peuvent travailler ensemble. Ce projet doit être réalisé dans les eaux extracôtières d'Eclipse Sound et de Milne Inlet, dans la région de Qikiqtaaluk Nunavut. La communauté la plus proche du site du projet proposé est Pond Inlet, au Nunavut. Il est proposé que le projet se déroule pendant les périodes les plus libres de la glace, à savoir l'été et le début de l'automne (entre fin juillet et fin octobre, si le temps le permet).

Personnel

Personnel on site: 1

Days on site: 0

Total Person days: 0

Operations Phase: from 2019-07-17 to 2019-10-24

Hulilukaarutit

Inigiya	Hulilukaarut Qanurittuq	Nunannga Qanurittaakhaanik	Initurlinga qanuritpa	Initurlinga utuqqarnitat unaluuniit Ingilraaqnitat Uyarangnuqtut akhuurninnga	Qanitqiayuq qanitqiamut nunallaat kitulluuniit ahiruqtailiyainnit nuna
Potential camera deployment extent	Researching	Marine	Marine waterway and transportation route; proposed Tallurutiup Imanga conservation area	N/A	Adjacent to Pond Inlet and Bylot Island Migratory Bird Sanctuary

Nunaliin Ilauyun, Aviktuqhimiayuniitunullu Ikayuuhiarunguyun

Nunauyuq	Atia	Timiuyuq	Upluani Uqaqatigyaungmata
Information is not available			

Angiuttauvaktunik

Naunaiqlugu nunanga talvani havauhikhaq ittuq:

Transboundary
North Baffin

Angiuttauvaktunik

Munariniqmut Ayuittiaqtuq	Angirutinga Qanurittuq	Tadja Qanurittaakhaanik	Ublua Tuniyayuq/Uuktuqtuq	Umikvikhaa Ublua
Alaanut	Nunavut Planning Commission	Active	2019-07-17	

Project transportation types

Transportation Type	Qanuq Atuqtauniarmangaa	Length of Use
Water	The researcher will be aboard the MVS Botnica icebreaker during this project.	

Project accomodation types

Alaanut,

Ihuaqutivaluin Atuqtauyukhan

Hanalrutit atuqtaunahuat (ukuallu ikuutat, pampiutainnik, tingmitinik, akhaluutinik, hunaluuniit)

Hanalrutit Qanurittuq	Qaffiuyut	Aktikkulaanga – Qanurittullu	Qanuq Atuqtauniarmangaa
baited underwater camera and frame	1	0.5 m3, 100 kg	We propose to deploy a remote baited remote underwater video camera lander to document fish and invertebrates on the sea floor. The device observes but does not collect specimens, making it a very low impact equipment.

Qanurittuq Urhuqyuaq unalu Qayangnaqtut Hunavaluit Aturninnga

Qanurittuq urhuqyuaq hunavaluit aturninnga:	Urhuqyuaq Qanurittuq	Qaffiuyut qattaryut	Qattaryuk Aktikkulaanga	Atauttimut Qaffiuyut	Ilanga	Qanuq Atuqtauniarmangaa
Information is not available						

Imaqmik Aturninnga

Ubluq qanuraaluk (m3)	Aturumaya inimavaluin utiqtittagaani qanuq	Atulirumaya inimavaluin utiqtittagani humi
0		

Iqqakuq

Ikkakunik Munakgiyauyunik

Havauhikhaq Hulilukaarut	Qanurittuq Iqqakut	Ihumagiyaayuq Qanuraaluktut Atuqtait	Qanuq Iqqakuurniarmangaa	Halummaqtirarnirutikan piyutin
Information is not available				

Avatiliriniqmut Ayurhautingit:

No environmental impacts are anticipated from this work. At-sea operations will be at the discretion of the Captain in coordination with their primary activity to escort iron ore transport ships.

Additional Information

SECTION A1: Project Info

SECTION A2: Allweather Road

SECTION A3: Winter Road

SECTION B1: Project Info

SECTION B2: Exploration Activity

SECTION B3: Geosciences

SECTION B4: Drilling

SECTION B5: Stripping

SECTION B6: Underground Activity

SECTION B7: Waste Rock

SECTION B8: Stockpiles

SECTION B9: Mine Development

SECTION B10: Geology

SECTION B11: Mine

SECTION B12: Mill

SECTION C1: Pits

SECTION D1: Facility

SECTION D2: Facility Construction

SECTION D3: Facility Operation

SECTION D4: Vessel Use

SECTION E1: Offshore Survey

SECTION E2: Nearshore Survey

SECTION E3: Vessel Use

SECTION F1: Site Cleanup

SECTION G1: Well Authorization

SECTION G2: Onland Exploration

SECTION G3: Offshore Exploration

SECTION G4: Rig

SECTION H1: Vessel Use

Aboard MSV Botnica, an icebreaker tasked with escorting iron ore ships into and out of Milne Inlet .

SECTION H2: Disposal At Sea

No disposal at sea.

SECTION I1: Municipal Development

Qanurittuq Ittunik Avatinga: Avatingalluanga

Marine waters to 1000 m depth

Qanurittuq Ittunik Avatinga: Inuuhimayunut Avatinga

Tallurutiup Imanga region serves as an important area for marine mammals and birds due to local highly productive Arctic waters.

Qanurittuq Ittunik Avatinga: Inungit-maniliurutingit Avatinga

Adjacent to Pond Inlet and to the Baffinland Mary's River mining operation.

Miscellaneous Project Information

Naunaiyainiq ukuninnga Ayurhautingit unalu Piumayaat Ikikliyuumiutinahuarutit

Tamatkiumayunik Ihuikgutivaktunik

None anticipated.

Impacts

Ilitariyauniq Avatiliriniqmut Ayurhautingit

PHYSICAL																			
Designated environmental areas																			
Ground stability																			
Permafrost																			
Hydrology / Limnology																			
Water quality																			
Climate conditions																			
Eskers and other unique or fragile landscapes																			
Surface and bedrock geology																			
Sediment and soil quality																			
Tidal processes and bathymetry																			
Air quality																			
Noise levels																			
BIOLOGICAL																			
Vegetation																			
Wildlife, including habitat and migration patterns																			
Birds, including habitat and migration patterns																			
Aquatic species, incl. habitat and migration/spawning																			
Wildlife protected areas																			
SOCIO-ECONOMIC																			
Archaeological and cultural historic sites																			
Employment																			
Community wellness																			
Community infrastructure																			
Human health																			
Havakvinga		-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
Aulapkaininnga		-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
Piiqtauniq		-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-

(P = Nakuuyuq, N = Nakuungittut unalu mikhilimaittuq, M = Nakuungittut unalu mikhittaaqtuq, U = Naluyaayuq)

Havaariyauyukhamut Nayugaa



List of Project Geometries

1	polyline	Potential camera deployment extent
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